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Myobock & Bebionic. ¹Suggested Coding Options.

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Base Code Options (includes Socket, Forearm, Charger, and Switch/Myoelectric Control)	, Humeral Section, Shoulder Bulkhead, Cables, Batteries,
Transcarpal switch/myo	L6026
Wrist Disarticulation switch/myo	L6920/L6925
Below Elbow switch/myo	L6930/L6935
Elbow Disarticulation switch/myo	L6940/L6945
Above Elbow switch/myo	L6950/L6955
Shoulder Disarticulation switch/myo	L6960/L6965
Interscapular-Thoracic switch/myo	L6970/L6975
Replacement Socket (molded to patient mode	el, with/without external power)
Replacement Socket	L6883 (BE/WD), L6884 (ED/AE), L6885 (SD/IT)
ocket Additions (add as appropriate, not all i	inclusive)
Test Sockets	L6680 (WD/BE), L6682 (ED/AE), L6684 (SD/IT)
Ultralight Material	L7400 (WD/BE), L7401 (ED/AE), L7402 (SD/IT)
Acrylic	L7403 (WD/BE), L7404 (ED/AE), L7405 (SD/IT)
ocket Additions: Suspension, Inserts, Liners	
Socket Additions	
Suction Socket	L6686
Frame Socket (includes flexible inner socket)	L6687 (WD/BE), L6688 (ED/AE), L6689 (SD), L6690 (IT)
Inserts	
*Removable Insert (e.g. Thermolyn/ Bocklite)	L6691
*Silicone Insert (e.g., Proflex with Silicone)	L6692

Liners

*14Y1 Silicone Arm Liner, prefab	L6694 Socket insert for use with locking mechanism	
*14Y5 Silicone Liner w/ CVD coating, prefab		
14A1 Lock Set	L6698 locking mechanism	
*6Y416 Custom Shape Plus UE Urethane Liner (made from positive model)	For Initial Liner use: L6696 Custom insert, congenital/atypical traumatic or L6697 Custom insert, other than congenital/ atypical traumatic	
*6Y417 Custom Shape Plus Urethane UE Replacement Liner (made from same model)	For Replacement Liner (same mold) use: L6694 Socket insert for use with locking mechanism or L6695 Socket insert not for use with locking mechanism	
*88L1 Custom Silicone TR Liner	Contact 800 328 4058 / reimbursement911@ottobock.com	

*Medicare limits the total number of inserts that a patient can have to 2 at any given time (including liners).

Pattern Recognition

13E520 Myo Plus TR compatible with: bebionic Hand SensorHand Speed MyoBock Variplus DMC VariPlus Electric Greifer 10V40 MyoWrist 2 10S17 Electric Wrist Rotator

*We do not recommend billing Medicare for the Myo Plus until specific coding is secured. *L7499 Addition to upper extremity external powered myoelectric prostheses; Ottobock 13E520 Myo Plus TR pattern recognition system; Multi-factor, layered processing of the user's amplified natural EMG signal patterns captured by a multiple electrode array to produce patient-specific rule set algorithms, allowing Myo Plus to recognize individual patient muscle signal patterns which are translated to intuitively control several prosthetic hand functions/grip types and/or several prosthetic devices (e.g. prosthetic hand, wrist rotator, wrist flexion/extension) instantaneously. The microprocessor integrates system calibration, signal quality evaluation, filtering, conditioning, processing, recognition of multiple muscle activation patterns, and transmission of complex functional controls.

See the Myo Plus TR Reimbursement Guide at: Myo Plus TR | Myo Plus TR & Electrodes | Myo Plus | Upper Limb Prosthetics | Prosthetics | Ottobock US Shop

Elbow Options	ow Options		
12K100N D	ynamic Arm	L6693 Forearm Counterbalance (use L7180/L7181 for MP Control)	
12K110N D	ynamic Arm Plus	L6693 Forearm Counterbalance (use L7181 for MP Control)	
12K44 Erge	oArm Hybrid plus	L6693 Forearm Counterbalance	
12K50 Ergo	oArm Electronic Plus	L6693 Forearm Counterbalance + L6638 Electric Lock	
Electric Hand and	l Greifer Options		
Bebionic	Bebionic Hand (Configurator: BB1000=O_B)		
8E70=*	Bebionic Hand with Electric QD Wrist L6880		
8E72=*	Bebionic Hand with Flexion Wrist L6880 + L6621		
8E71=*	Bebionic Hand with Short PDAC Verified	Wrist L6880	
	- See rotation wrist o	option below.	

- L6629 may be added to the prosthesis for a lamination collar with coupling used for quick disconnect for terminal device interchange, cleaning, or servicing (8E70/8E72)

DMC Plus		
8E38=6	System Electric Hand DMC plus with QD wrist	L7007 + L6882
8E39=6	System Electric Hand DMC plus with Lamination	L7007 + L6882
	Ring	
8E41=6	System Electric Hand DMC plus with Threaded	L7007 + L6882
	Stud	
8E44=6	Transcarpal Hand DMC plus w/Lam Plate	L7007 + L6882
8E44=6-*-F	Transcarpal Hand DMC plus with MyoFlex QD	L7007 + L6882 + L6621
	Wrist	
		(For Quick Disconnect see coding
		below)
Digital Twin		
8E38=7	System Electric Hand Digital Twin with QD wrist	L7007 + L6882
8E38=7	System Electric Hand Digital Twin with	L7007 + L6882
	Lamination Ring	

8E44=7-*	Wrist	tal Twin with MyoFlex QD	L7007 + L6882 + L6621 (For Quick Disconnect see coding below)
Sensor Ha	nd Speed		
8E38=8	SensorHand Speed wit	th QD Wrist	L7007 + L6881 + L6882
8E39=8	SensorHand Speed wit	th Lamination Ring	L7007 + L6881 + L6882 (For Quick Disconnect see coding below)
VariPlus S	peed		
8E38=9	MyoHand VariPlus Spe	ed w/ QD wrist	L7007 + L6882
8E39=9	MyoHand VariPlus Spe	ed w/ Lam. Ring	L7007 + L6882
8E41=9	MyoHand VariPlus Spe	ed w/ Thread Stud	L7007 + L6882
8E41=9-F	MyoHand Vari Plus Speed w/ MyoFlex QD Wrist		L7007 + L6882 + L6621 (For Quick Disconnect see coding below)
Electric G	reifers		
8E33=9-1	Sys Electric Greifer DMC Wrist	Sys Electric Greifer DMC VariPlus w/Flex/Ext QD Wrist	
8E34=9-1	Sys Electric Greifer DMC	Sys Electric Greifer DMC VariPlus with Lam. Ring	
Pincer (if	used, addition to termina	al device)	
8Y1	Pincer		L6810 Precision Pinch Device
onal Wrist O	ptions		
10S17 Elect 13E205 Myoł	ric Wrist Rotator Rotronic	L7259 Electronic Wrist MyoRotronic Controlle	: Rotator r is included in the base code.
10V40 Myo	Wrist 2 Act	L6621 Flexion/Extensio device	on Wrist for external powered
Disconnect	(add to prosthesis when us	sed for terminal device inte	erchange, cleaning, servicing)
10S1* Lami Coupling pi	nation Collar + 10S4 ece	L6629 Lamination coll	ar with coupling
der Options			
12S6 Movos	Shoulder Swing	positional locking, flexi	addition, shoulder joint, multi- on, adjustable abduction friction ody powered or external powered

Harness Options	
21A35=1 AE Harness, Triple Control,	L6677 Harness, triple ctrl, simultaneous operation of TD &
Perlon	elbow
21A35=2 AE Harness, Triple Control,	
Steel	
21A47 Active TH Harness	L6672 Harness chest or shoulder, saddle type
Armloop for 21A47	Armloop included in L6672
Additional Switch Options	
9X14 Harness Pull Switch	L6611 External powered, additional switch, any type
9X18 Cable Pull Switch	
9X25 Rocker Switch	
9X37 Pressure Switch	
9X50 & 9X52 Linear Transducer	
Donning Sheath	
OC1560=* Donning Sheath EasyFit	L7600 Prosthetic donning sleeve
Arm	
Glove Options	
8S711=* Bebionic Silicone Glove	L6890 Glove for terminal device, any material
8S710=* Bebionic Black Glove	
8S11N Myoskin Natural 8S11 /12 /13 /20 Cosmetic Glove	
Replacement Electrodes (initial electrodes incl	ludad in basa coda)
13E200 /202 Electrodes	
	L7510 Repair of prosthetic device, replace minor parts
13E400 /401 Remote Electrodes	
13Z161 /162 /163 Electrode Domes 6 pk	
13E129=* Cable	
Replacement Battery/Charger (initial battery a	
757B35 MyoEnergy Integral	L7367 Lithium-ion battery, replacement
757B20/21 Energy Pack	
757L35 MyoCharge Integral	L7368 Lithium-ion battery charger, replacement
757L20 Li-Ion Charger	
757B15 X-ChangePack	L7360 Battery 6 volt, each
757L14 Pulse Charger	L7362 Battery charger 6 volt, each

Ottobock's reimbursement team is here to help with your upper extremity coding. Call us at 800 328 4058, or email your request to Reimbursement911@ottobock.com

¹ The product/device "Supplier" (defined as an O&P practitioner, O&P patient care facility, or DME supplier) assumes full responsibility for accurate billing of Ottobock products. It is the Supplier's responsibility to determine medical necessity; ensure coverage criteria is met; and submit appropriate HCPCS codes, modifiers, and charges for services/products delivered. It is also recommended that Supplier's contact insurance payer(s) for coding and coverage guidance prior to submitting claims. Ottobock Coding Suggestions and Reimbursement Guides do not replace the Supplier's judgment. These recommendations may be subject to revision based on additional information or alpha-numeric system changes.

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